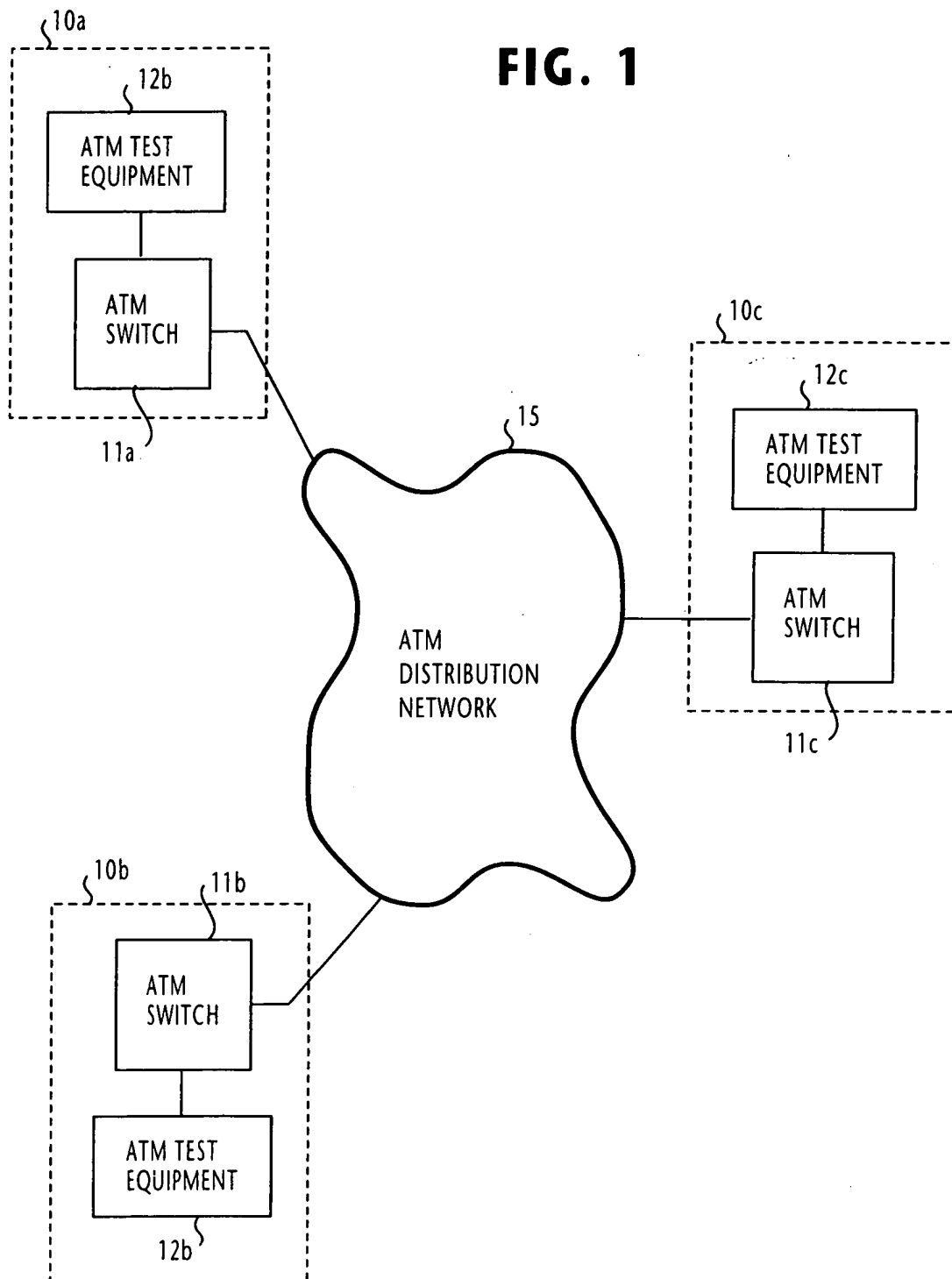
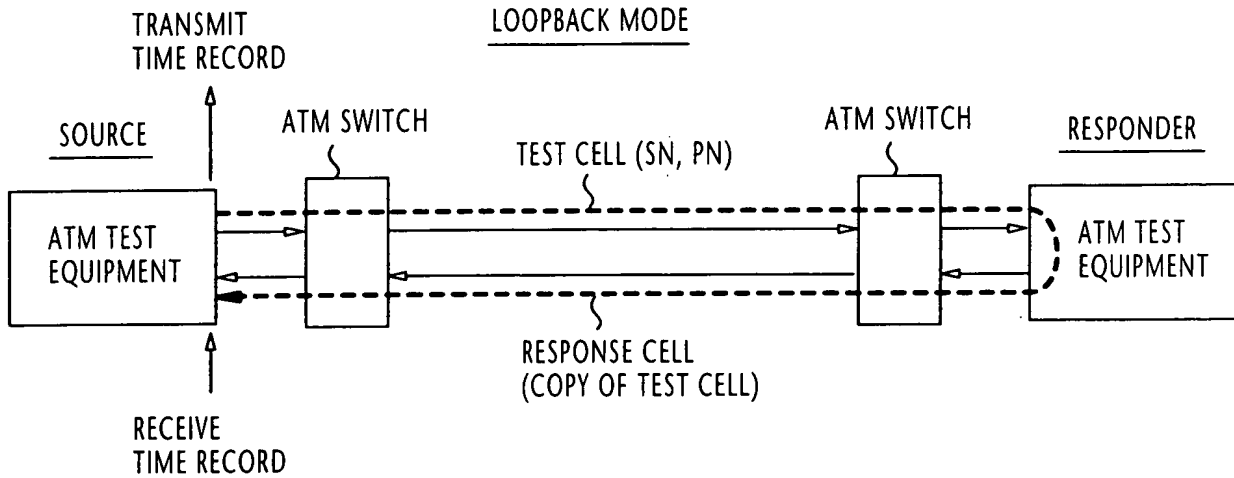
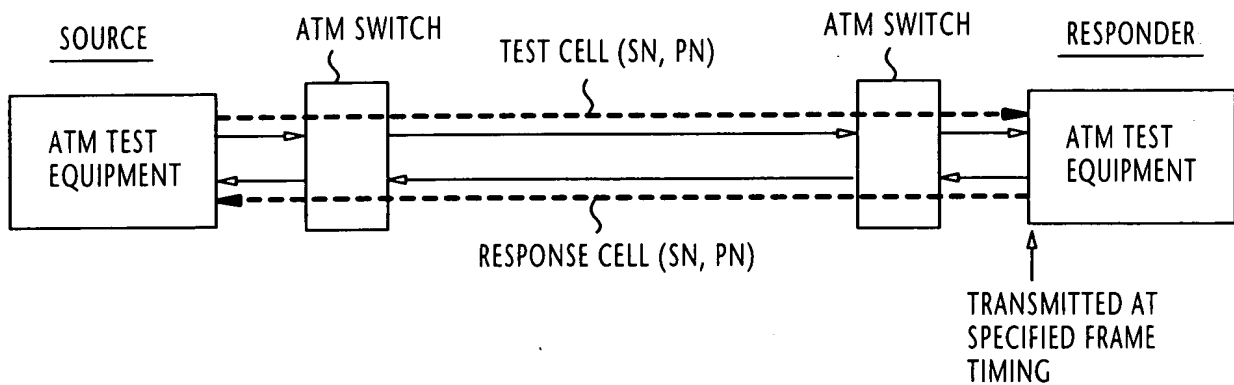
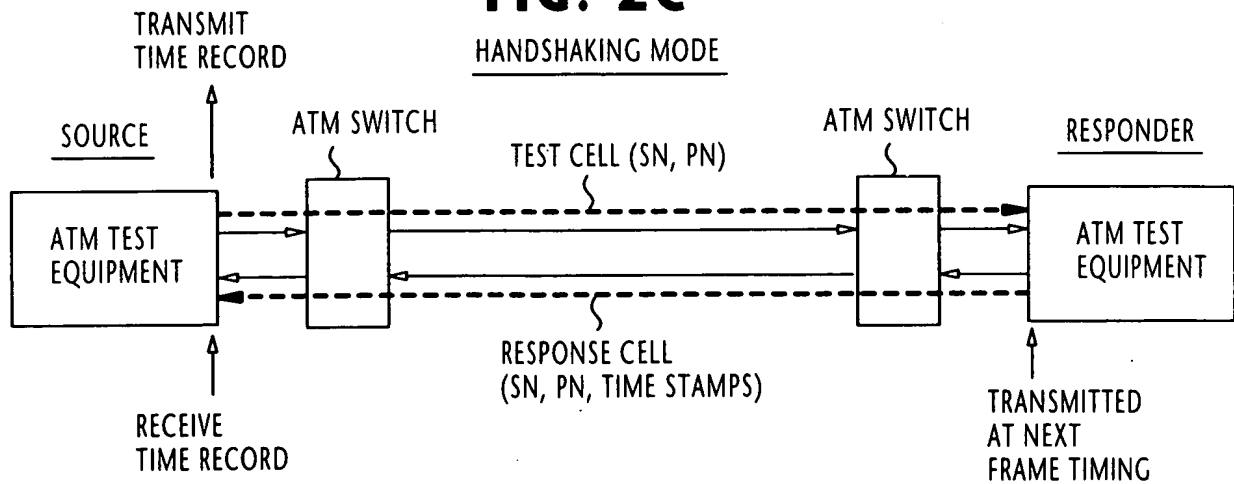
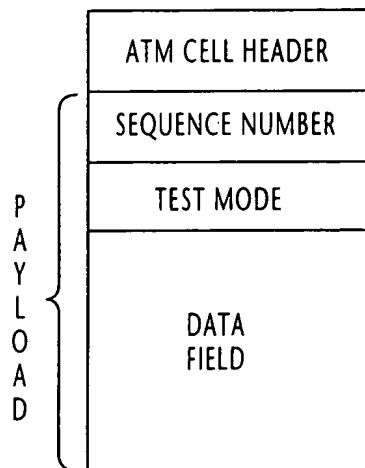
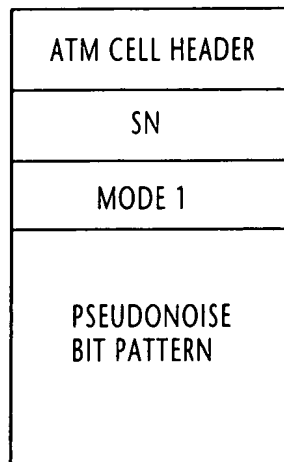


**FIG. 1**

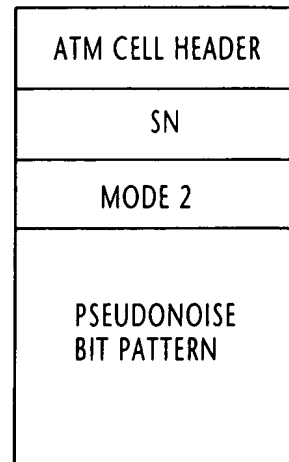
**FIG. 2A**LOOPBACK MODE**FIG. 2B**TWO-WAY MODE**FIG. 2C**HANDSHAKING MODE

**FIG. 3A****FIG. 3B**

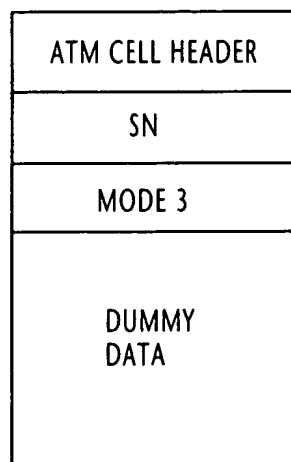
SOURCE AND RESPONDER  
NODES (LOOPBACK MODE)

**FIG. 3C**

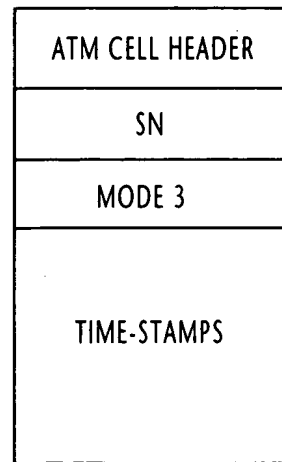
SOURCE AND RESPONDER  
NODES (TWO-WAY MODE)

**FIG. 3D**

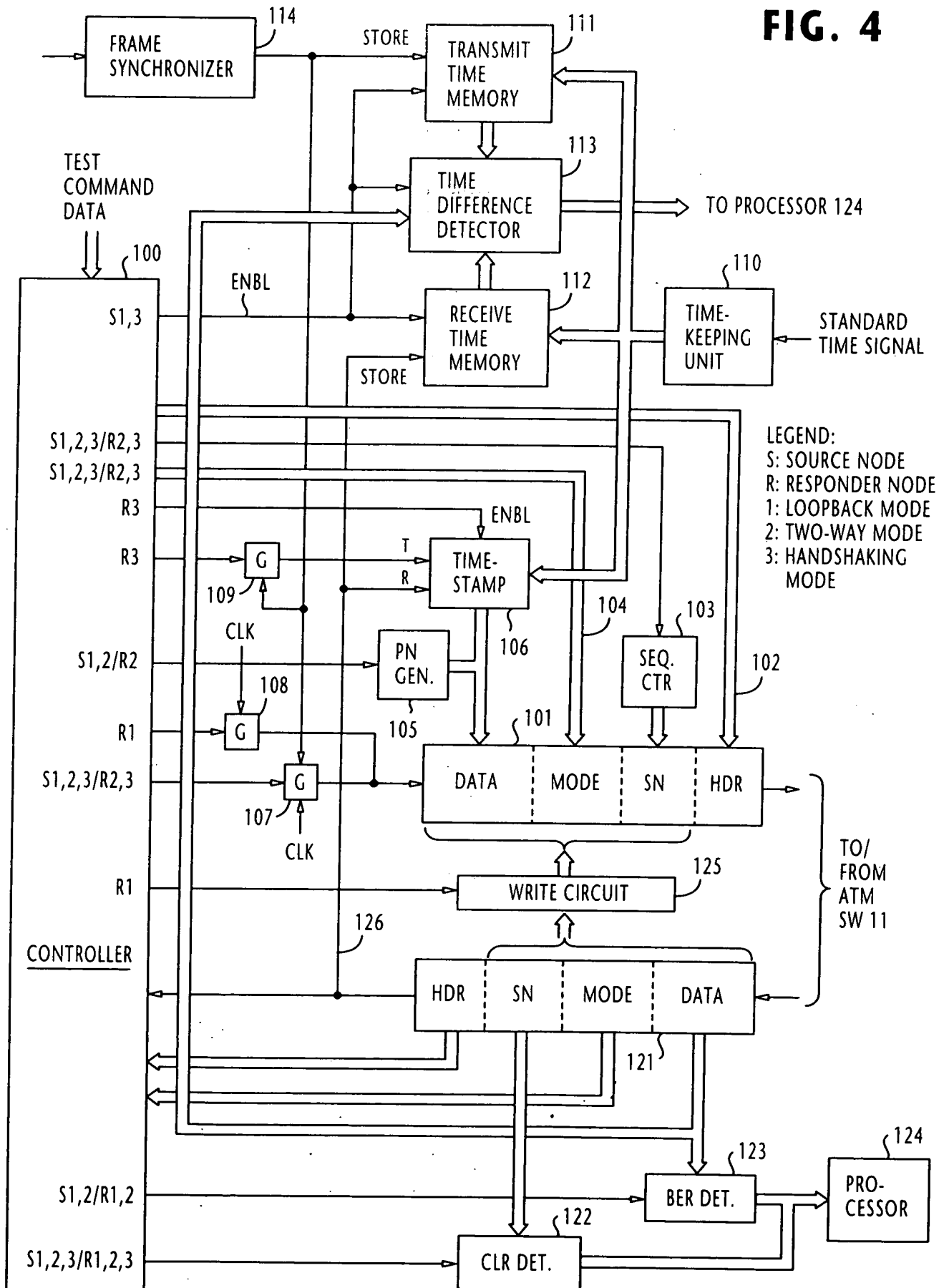
SOURCE NODE  
(HANDSHAKING MODE)

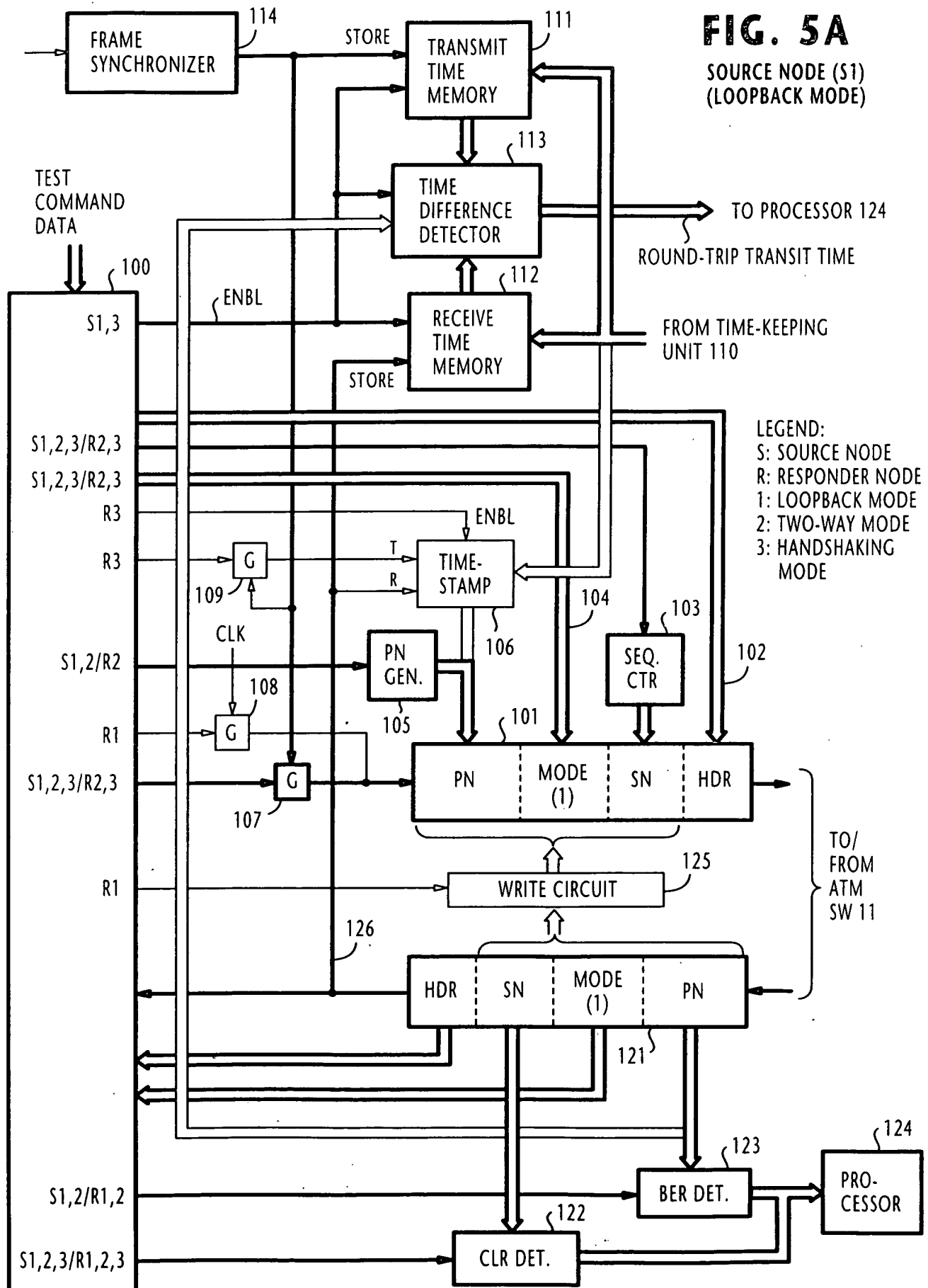
**FIG. 3E**

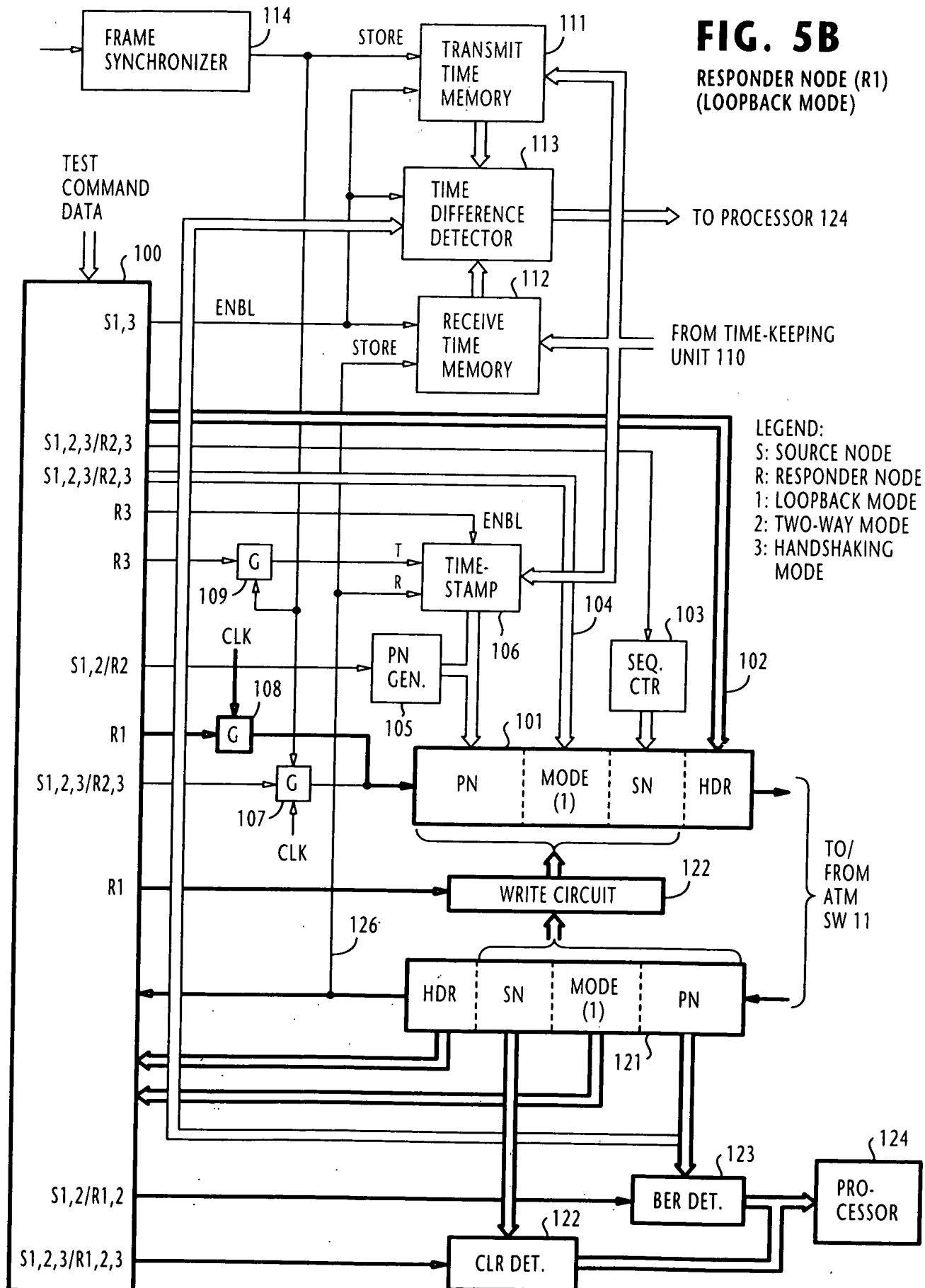
RESPONDER NODE  
(HANDSHAKING MODE)

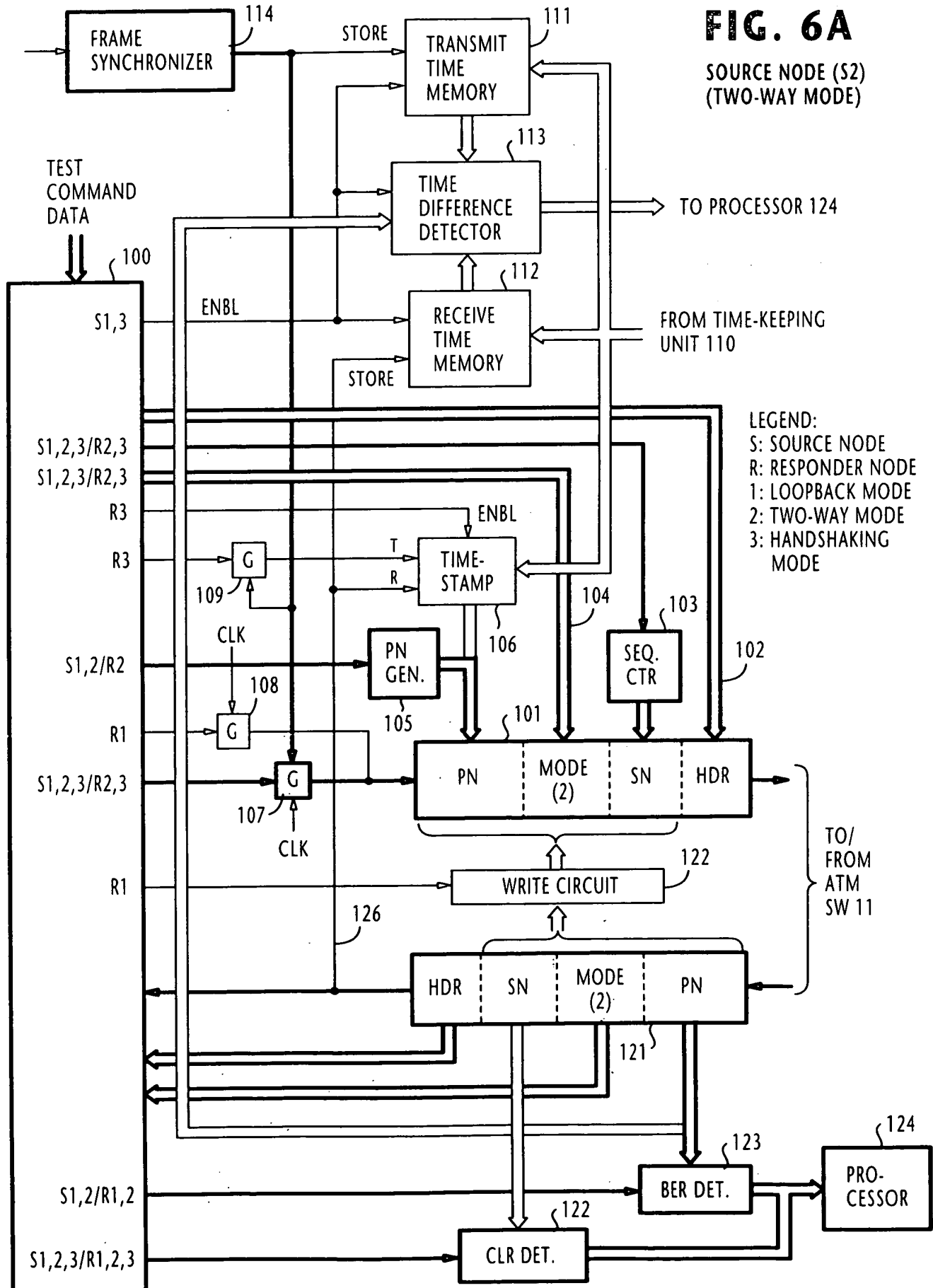


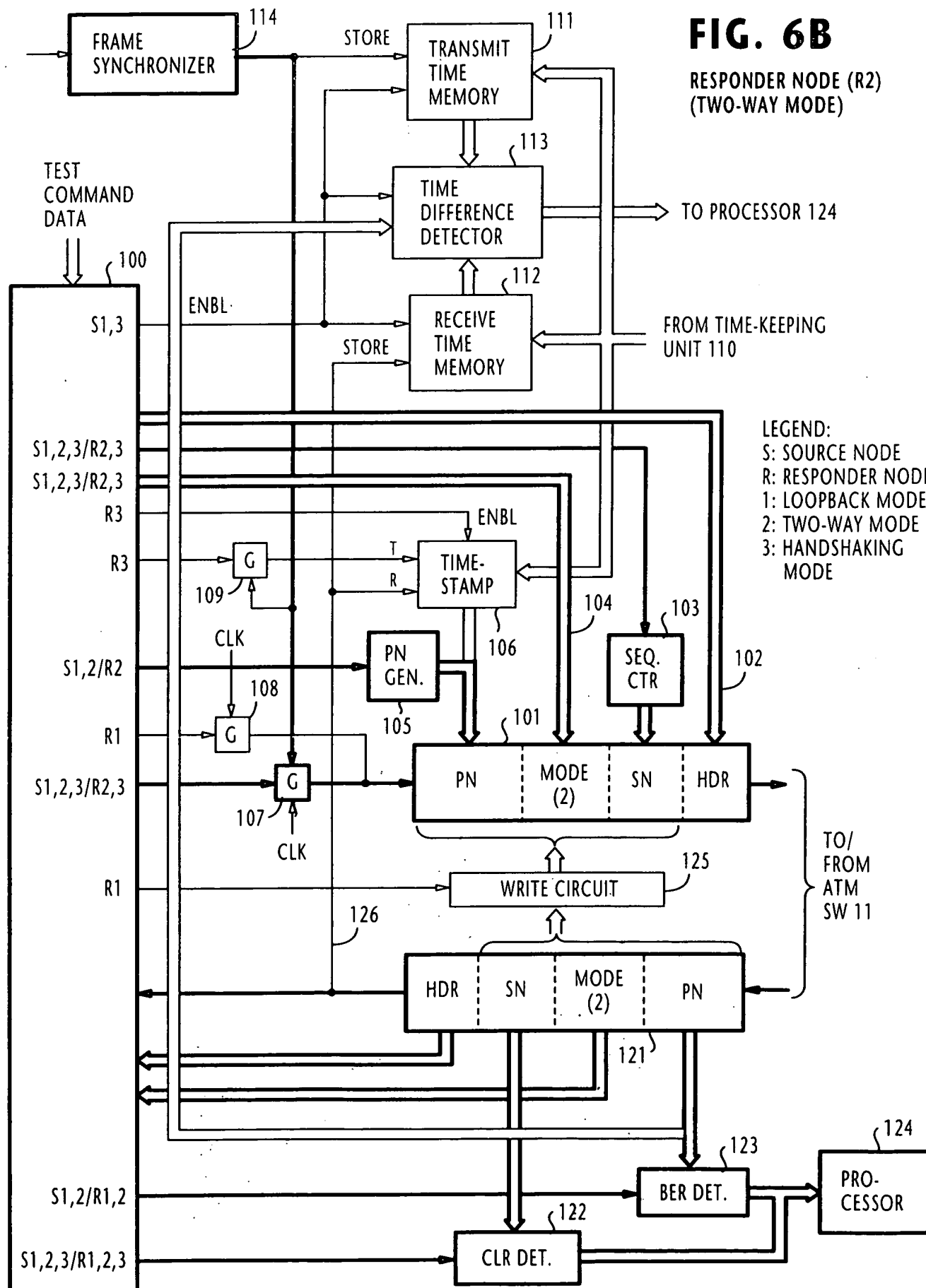
**FIG. 4**



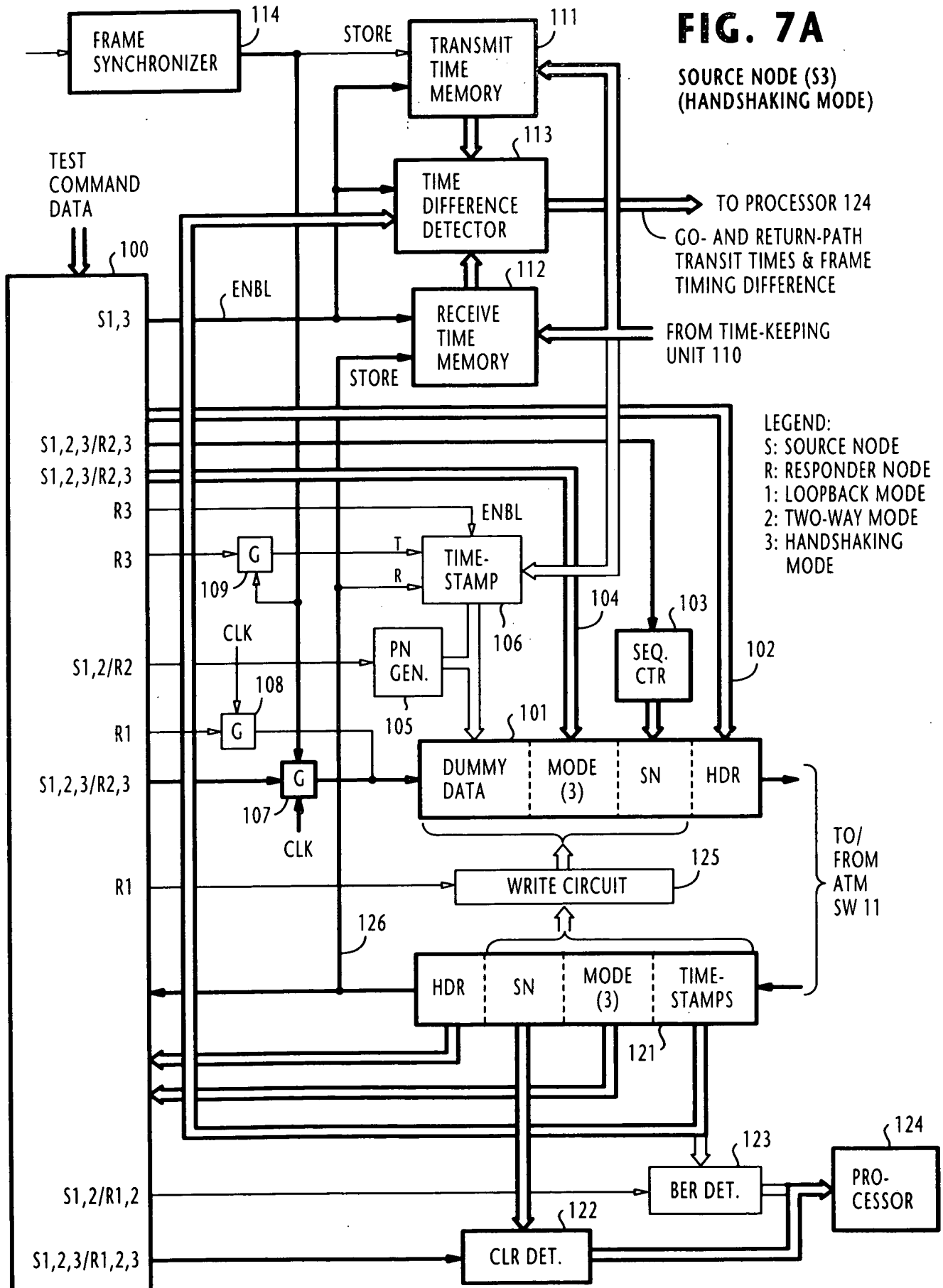
**FIG. 5A**SOURCE NODE (S1)  
(LOOPBACK MODE)

**FIG. 5B****RESPONDER NODE (R1)  
(LOOPBACK MODE)**

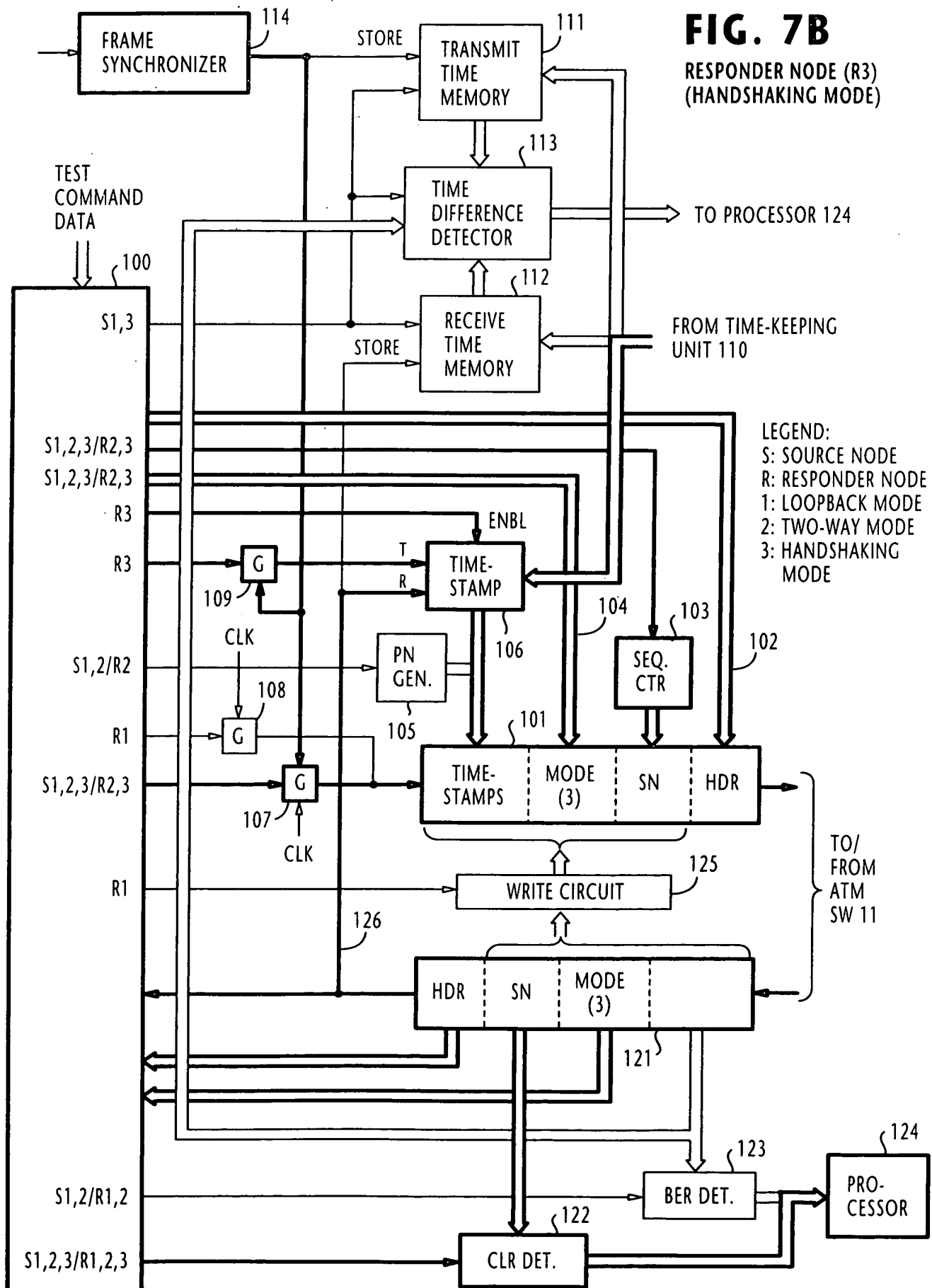
**FIG. 6A****SOURCE NODE (S2)  
(TWO-WAY MODE)**

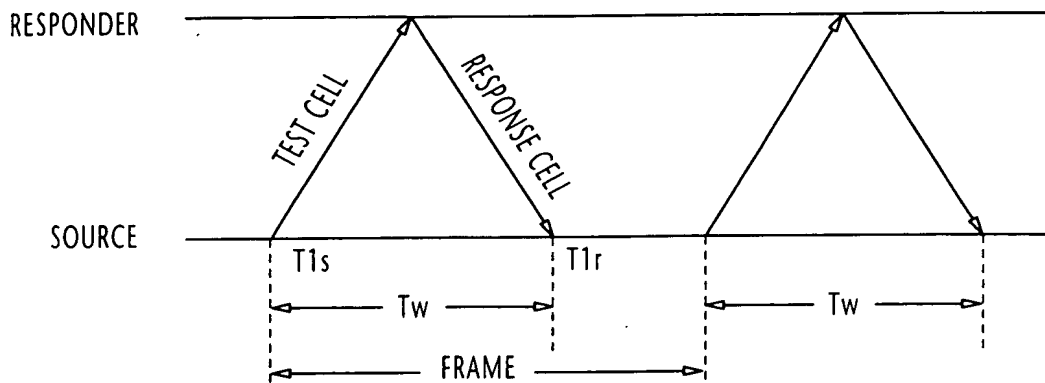
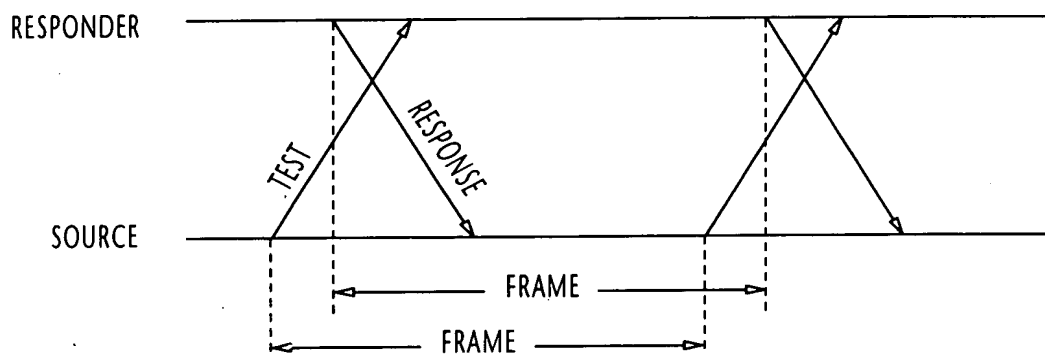
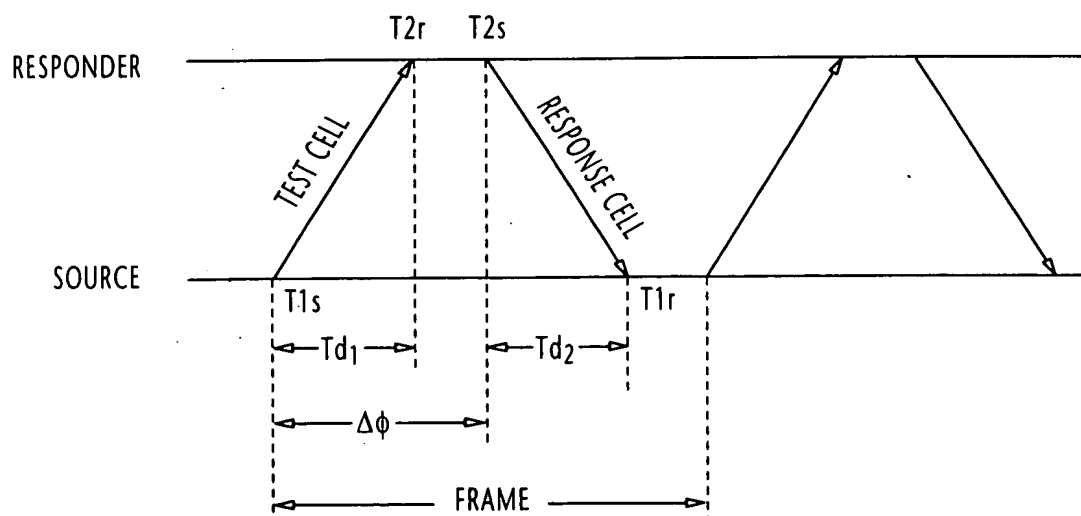
**FIG. 6B****RESPONDER NODE (R2)  
(TWO-WAY MODE)**

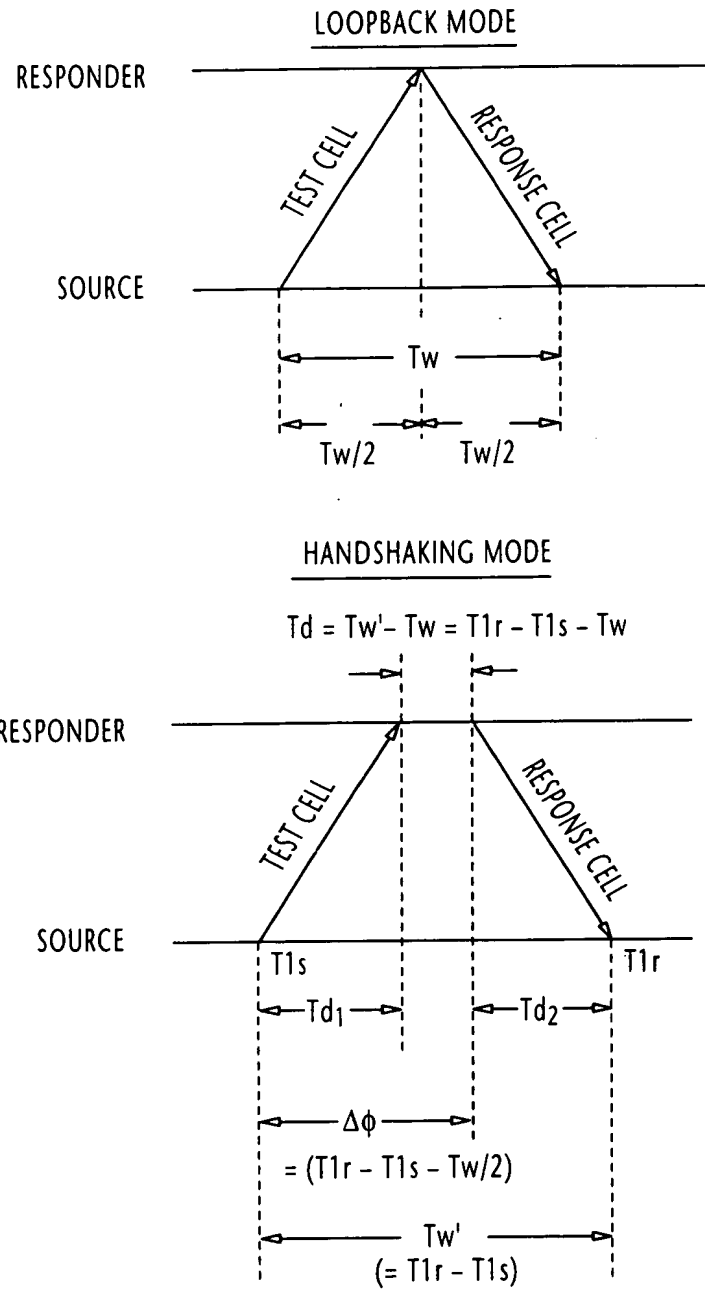


**FIG. 7A****SOURCE NODE (S3)  
(HANDSHAKING MODE)**

**FIG. 7B**  
**RESPONDER NODE (R3)**  
**(HANDSHAKING MODE)**



**FIG. 8A** LOOPBACK MODE**FIG. 8B** TWO-WAY MODE**FIG. 8C** HANDSHAKING MODE

**FIG. 9**

$$T_{d1} = \Delta\phi - T_d = \Delta\phi - (T_{1r} - T_{1s} - T_w)$$

$$T_{d2} = T_w' - \Delta\phi = T_{1r} - T_{1s} - \Delta\phi$$

**FIG. 10**